Some New Iterative Methods Based on Composite Trapezoidal Rule for Solving Nonlinear Equations

Ogbereyivwe Oghovese¹, Emunefe O. John²

¹(¹Department of Mathematics and Statistics, Delta State Polytechnic, Ozoro, Nigeria) ²(Department of General Studies, Petroleum Training Institute, Effurun, Delta State, Nigeria)

ABSTRACT: In this paper, new two steps family of iterative methods of order two and three constructed based on composite trapezoidal rule and fundamental theorem of calculus, for solving nonlinear equations. Several numerical examples are given to illustrate the efficiency and performance of the iterative methods; the methods are also compared with well known existing iterative method.

KEYWORDS: Nonlinear equations, computational order of convergence, Newton's method

I. INTRODUCTION

Solving nonlinear equations is one of the most predominant problems in numerical analysis. A classical and very popular method for solving nonlinear equations is the Newton's method. Some historical points on this method can be found in [1]. Recently, some methods have been proposed and analyzed for solving nonlinear equations [2-13]. Some of these methods have been suggested either by using quadrature formulas, homotopy, decomposition or Taylor's series [2-13]. Motivated by these techniques applied by various authors [2-13] and references therein, in constructing numerous iterative methods for solving nonlinear equations, we suggest a two steps family of iterative method based on composite trapezoidal rule and fundamental theorem of calculus for solving nonlinear equations. We also considered the convergence analysis of these methods. Several examples of functions, some of which are same as in [2-13] were used to illustrate the performance of the methods and comparison with other existing methods.

II. PRELIMINARIES

We use the following definitions:

Definition 1. (See Dennis and Schnable [2]) Let $\alpha \in \mathbb{R}$, $x_n \in \mathbb{R}$, n = 0,1,2,... Then, the sequence $\{x_n\}$ is said to converge to α if

$$\lim_{n \to \infty} |x_n - \alpha| = 0 \tag{1}$$

If, in addition, there exists a constant $c \ge 0$, an integer $x_0 \ge 0$, and $p \ge 0$ such that for all $n \ge x_0$, $|x_{n+1} - \alpha| \le c |x_n - \alpha|^p$ (2)

then
$$\{x_n\}$$
 is said to converge to α with q-order at least p. If $p = 2$, the convergence is said to be of order 2.

Definition 2 (See Grau-Sanchez et al. [14]) The computational local order of convergence, $\overline{\rho_n}$, (CLOC) of a sequence $\{x_n\}_{n\geq 0}$ is defined by

$$\overline{\rho_n} = \frac{\log|e_n|}{\log|e_{n-1}|},\tag{3}$$

where x_{n-1} and x_n are two consecutive iterations near the roots α and $e_n = x_{n-1} - \alpha$.

Notation 1: (See [6]) The notation
$$e_n = x_n - \alpha$$
 is the error in the n^{th} iteration. The equation
$$e_{n+1} = ce_n^p + O(e_n^{p+1}).$$
(4)

is called the error equation. By substituting $e_n = x_n - \alpha$ for all n in any iterative method and simplifying, we obtain the error equation for that method. The value of p obtained is called the order of this method.

III. **DEVELOPMENT OF THE METHODS**

Consider a nonlinear equation

f(x) = 0By the Fundamental Theorem of Calculus, if f(x) is continuous at every point of [a, b] and F is any antiderivatives of f(x) on [a, b], then

$$\int_{a}^{b} f(x) \, dx = F(b) - F(a) \tag{6}$$

Differentiating both side of (6) with respect to x, we have;

$$f(x) = f(b) - f(a) \tag{7}$$

where f(b) and f(a) are derivatives of F(b) and F(a) respectively.

Recall the Composite Trapezoidal rule given by;

$$\int_{a}^{b} f(x) dx = \frac{b-a}{2n} \left[f(a) + 2 \sum_{i=1}^{n-1} f_i + f(b) \right]$$
(8)

If n = 2 in (8) we have;

$$\int_{a}^{b} f(x) \, dx = \frac{b-a}{4} \left[f(a) + 2f\left(\frac{a+b}{2}\right) + f(b) \right] \tag{9}$$

Differentiating (9) with respect to x, we have;

$$f(x) = \frac{b-a}{4} \left[f'(a) + 2f'\left(\frac{a+b}{2}\right) + f'(b) \right]$$
(10)

Equating (7) and (10) we have;

$$f(b) - f(a) = \frac{b-a}{4} \left[f'(a) + 2f'\left(\frac{a+b}{2}\right) + f'(b) \right]$$
(11)

From(5), we have;

$$x = a - 4\frac{f(a)}{f'(a)} - (x - a)\frac{f'(x)}{f'(a)} - 2(x - a)\frac{f'\left(\frac{a + b}{2}\right)}{f'(a)}$$
(12)

Using (12), one can suggest the following iterative method for solving the nonlinear equation (5).

Algorithm 1: Given an initial approximation x_0 (close to α the root of (5)), we find the approximate solution x_{n+1} by the implicit iterative method: $(r \perp r)$

$$x_{n+1} = x_n - 4\frac{f(x_n)}{f'(x_n)} - (x-a)\frac{f'(x_{n+1})}{f'(x_n)} - 2(x-a)\frac{f'\left(\frac{x_n + x_{n+1}}{2}\right)}{f'(x_n)}, \quad n = 0, 1, 2, \dots$$
(13)

The implicit iterative method in (13) is a predictor-corrector scheme, with Newton's method as the predictor, and Algorithm 1 as the corrector. The first consequence of (13) is the suggested two-step iterative method for solving (5) stated as follows:

Algorithm 2: Given an initial approximation x_0 (close to α the root of (5)), we find the approximate solution x_{n+1} by the iterative schemes:

$$y_n = x_n - \frac{f(x_n)}{f'(x_n)} \tag{14a}$$

$$x_{n+1} = x_n - 4\frac{f(x_n)}{f'(x_n)} - (y_n - x_n)\frac{f'(y_n)}{f'(x_n)} - 2(y_n - x_n)\frac{f'\left(\frac{x_n + y_n}{2}\right)}{f'(x_n)}, \quad n = 0, 1, 2, \dots$$
(14b)

From (14a), we have that;

$$y_n - x_n = -\frac{f(x_n)}{f'(x_n)}$$
(15)

Using (15) in (14b) we suggest another new iterative scheme as follows:

Algorithm 3: Given an initial approximation x_0 (close to α the root of (5), we find the approximate solution x_{n+1} by the iterative schemes:

$$x_{n+1} = x_n - 4\frac{f(x_n)}{f'(x_n)} + \left[\frac{f(x_n)}{f'(x_n)}\right]\frac{f'(y_n)}{f'(x_n)} - 2\left[\frac{f(x_n)}{f'(x_n)}\right]\frac{f'\left(\frac{x_n + y_n}{2}\right)}{f'(x_n)}, \quad n = 0, 1, 2, \dots$$
(16)

From (5) and (11) we can have the fixed point formulation given by

х

$$= a - \frac{4f(a)}{f'(a) + 2f'\left(\frac{a+x}{2}\right) + f'(x)}$$
(17)

The formulation (17) enable us to suggest the following iterative method for solving nonlinear equations.

Algorithm 4: Given an initial approximation x_0 (close to α the root of (5), we find the approximate solution x_{n+1} by the iterative schemes: *c* ()

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

$$x_{n+1} = x_n - \frac{4f(x_n)}{f'(x_n) + 2f'\left(\frac{x_n + y_n}{2}\right) + f'(y_n)}, \quad n = 0, 1, 2, \dots$$
(18)

In the next section, we present the convergence analysis of Algorithm 2 and 4. Similar procedures can be applied to analyze the convergence of Algorithm 3.

IV. **CONVERGENCE ANALYSIS OF THE METHODS**

Theorem 1: Let $\alpha \in I$ be a simple zero of sufficiently differentiable function $f: I \subseteq \mathbb{R} \to \mathbb{R}$ for an open interval I. If x_0 is sufficiently close to α , then the iterative method defined by (14) is of order two and it satisfies the following error equation:

$$e_{n+1} = \alpha - 3c_2e_n^2 + \left(c_3 + 6c_2^2 - \frac{3}{2}c_2\right)e_n^3 + O(e_n^3)$$
(19)

where

$$c_2 = \frac{f''(\alpha)}{2f'(\alpha)} \tag{20}$$

Proof Let α be a simple zero of f, and $e_n = x_n - \alpha$. Using Taylor expansion around $x = \alpha$ and taking into account $f(\alpha) = 0$, we get 2. 2. .

$$f(x_n) = f'(\alpha)[e_n + c_2e_n^2 + c_3e_n^3 + c_4e_n^4 + \cdots],$$

$$f'(x_n) = f'(\alpha)[1 + 2c_2e_n + 3c_3e_n^2 + 4c_4e_n^3 + 5c_5e_n^4 + \cdots]$$
(21)
(22)

where
$$c_k = \frac{f^k(\alpha)}{k!f'(\alpha)}, \ k = 2,3,4,...$$
 (23)

Using (21) and (22), we have;

$$\frac{f(x_n)}{f'(x_n)} = \left[e_n - c_2 e_n^2 + 2(c_2^2 - c_3)e_n^3 + (7c_2c_3 - 4c_2^3 - 3c_4)e_n^4 + \cdots\right]$$
(24)

But

$$y_n = x_n - \frac{f(x_n)}{f'(x_n)}$$
(25)
= $[\alpha + c_2 e_n^2 + 2(c_2^2 - c_3)e_n^3 - (7c_2 c_3 - 4c_2^3 - 3c_4)e_n^4 + \cdots]$ (26)

$$= [\alpha + c_2 e_n^2 + 2(c_2^2 - c_3)e_n^3 - (7c_2c_3 - 4c_2^3 - 3c_4)e_n^4 + \cdots]$$

Hence,

$$y_n - x_n = -e_n + c_2 e_n^2 + 2(c_2^2 - c_3)e_n^3 - (7c_2c_3 - 4c_2^3 - 3c_4)e_n^4 + \cdots$$
(27)

From (26), we have;

$$f'(y_n) = f'(\alpha) \left[1 + 2c_2^2 e_n^2 + 4(c_2 c_3 - c_2^3) e_n^3 + (-11c_2^2 c_3 + 6c_2 c_4 + 8c_2^4) e_n^4 + \cdots \right]$$
(28)

Combining (22) and (28), we have;

$$\frac{f'(y_n)}{f'(x_n)} = -2c_2e_n + (-3c_3 + 6c_2^2)e_n^2 + (-16c_2^3 - 4c_4 + 16c_2c_3)e_n^3 + \cdots$$
(29)

From (27) and (29) we have;

$$(y_n - x_n)\frac{f'(y_n)}{f'(x_n)} = -e_n + 3c_2e_n^2 + (5c_3 - 10c_2^2)e_n^3 + (-30c_2c_3 + 30c_2^3 + 7c_4)e_n^4 + \cdots (30)$$

From the relation;

$$\frac{x_n + y_n}{2} = x_n - \frac{f(x_n)}{2f'(x_n)}$$

= $\alpha + \frac{1}{2}e_n + \frac{1}{2}c_2e_n^2 - (c_2^2 - c_3)e_n^3 - \frac{1}{2}(7c_2c_3 - 4c_2^3 - 3c_4)e_n^4 + \cdots$ (31)
we have:

we have;

$$f\left(\frac{x_{n}+y_{n}}{2}\right) = f\left(x_{n}-\frac{f(x_{n})}{2f'(x_{n})}\right)$$

$$= f(\alpha)\left(\frac{1}{2}e_{n}+\frac{3}{4}c_{2}e_{n}^{2}+\left(-\frac{1}{2}c_{2}^{2}+\frac{9}{8}c_{3}\right)e_{n}^{3}+\left(\frac{5}{4}c_{2}^{3}-\frac{17}{8}c_{2}c_{3}+\frac{25}{16}c_{4}\right)e_{n}^{4}\right)$$

$$+\left(-3c_{2}^{4}+\frac{57}{8}c_{3}c_{2}^{2}-\frac{9}{4}c_{3}^{2}-\frac{13}{4}c_{2}c_{4}+\frac{65}{32}c_{5}\right)e_{n}^{5}+\cdots\right) (32)$$

$$f'\left(\frac{x_{n}+y_{n}}{2}\right) = f(\alpha)\left(1+c_{2}e_{n}+\left(c_{2}^{2}+\frac{3}{4}c_{3}\right)e_{n}^{2}+\left(-2c_{2}^{3}+\frac{7}{2}c_{2}c_{3}+\frac{1}{2}c_{4}\right)e_{n}^{3}\right)$$

$$+\left(\frac{9}{2}c_{2}c_{4}+c_{2}^{4}-\frac{37}{4}c_{2}^{2}c_{3}+3c_{3}^{2}+\frac{5}{16}c_{5}\right)e_{n}^{4}+\cdots (33)$$

Using (22) and (33) we have;

$$\frac{f'\left(\frac{x_n+y_n}{2}\right)}{f'(x_n)} = 1 - c_2 e_n + \left(3c_2^2 - \frac{3}{4}c_3 - 3c_3\right)e_n^2 + \cdots$$
(34)

And (27) with (34) gives;

$$(y_n - x_n) \frac{f'\left(\frac{x_n + y_n}{2}\right)}{f'(x_n)} = -e_n + 2c_2e_n^2 + \left(\frac{3}{4}c_2 + c_3 - 2c_2^2\right)e_n^3 + \cdots$$
(35)

Using (29), (30) and (35) in

$$x_{n+1} = x_n - 4 \frac{f(x_n)}{f'(x_n)} - (y_n - x_n) \frac{f'(y_n)}{f'(x_n)} - 2(y_n - x_n) \frac{f'\left(\frac{x_n + y_n}{2}\right)}{f'(x_n)}$$
$$= \alpha - 3c_2 e_n^2 + \left(c_3 + 6c_2^2 - \frac{3}{2}c_2\right) e_n^3 + O(e_n^4) \blacksquare$$
(36)

Thus, we observe that the Algorithm 2 is second order convergent.

Theorem 2: Let $\alpha \in I$ be a simple zero of sufficiently differentiable function $f: I \subseteq \mathbb{R} \to \mathbb{R}$ for an open interval I. If x_0 is sufficiently close to α , then the iterative method defined by (18) is of order three and it satisfies the following error equation:

$$e_{n+1} = \alpha + \left(\frac{1}{8}c_3 + c_2^2\right)e_n^3 + O(e_n^4)$$
(37)
(38)

where $c_3 = \frac{f''(\alpha)}{3!f'(\alpha)}$ **Proof** Using (22), (33) and (28) we have;

$$f'(x_n) + 2f'\left(\frac{x_n + y_n}{2}\right) + f'(y_n) = f'(\alpha) \left[\!\left[4 + 4c_2e_n + \left(\frac{9}{2}c_3 + 4c_2^2\right)e_n^2 + \left(5c_4 + 11c_2c_3 - 8c_2^3\right)e_n^3 + \left(-11c_2^2c_3 + 6c_2c_4 + 8c_2^4\right)e_n^4 + \cdots \right]\!\right]$$
(39)
nd from (21) we have:

and from (21) we have;

$$4f'(x_n) = f'(\alpha)[4e_n + 4c_2e_n^2 + 4c_3e_n^3 + 4c_4e_n^4 + \cdots]$$
(40)

Combining (39) and (40) in (18) gives;

$$e_{n+1} = x_n - \frac{4f(x_n)}{f'(x_n) + 2f'\left(\frac{x_n + y_n}{2}\right) + f'(y_n)}$$

= $\alpha + \left(\frac{1}{8}c_3 + c_2^2\right)e_n^3 + O(e_n^4)$ (41)

This means the method defined by (18) is of third-order. That completes the proof.

V. NUMERICAL EXAMPLES

In this section, we present some examples to illustrate the efficiency of our developed methods which are given by the Algorithm 1 – 4. We compare the performance of Algorithm 2 (AL2) and Algorithm 4 (AL4) with that of Newton Method (NM). All computations are carried out with double arithmetic precision. Displayed in Table 1 are the number of iterations (NT) required to achieve the desired approximate root x_n and respective Computational Local Order of Convergence (CLOC), $\overline{\rho_n}$. The following stopping criteria were used.

$$i. \quad |x_{n+1} - x_n| < \varepsilon \qquad ii. \quad f(x_{n+1}) < \varepsilon \tag{37}$$

where $\varepsilon = 10^{-15}$. We used the following functions, some of which are same as in [2-4,6-12,14]

$$\begin{cases} f_1(x) = (x-1)^3 - 1 \\ f_2(x) = \cos(x) - x \\ f_3(x) = x^3 - 10 \\ f_4(x) = x^2 - e^x - 3x + 2 \\ f_5(x) = (x+2)e^x - 1 \\ f_6(x) = x^3 + 4x^2 - 10 \\ f_7(x) = \ln x + \sqrt{x} - 5 \\ f_8(x) = e^x \sin x + \ln (x^2 + 1) \end{cases}$$
(38)

Table 1: Comparison between methods depending on the number of iterations (IT) and Computational Local Order of Convergence.

f(x)	x_0	Number of iterations (NT)			Computational Local Order of Convergence (CLOC)		
		NM	<i>AL</i> 2	<i>AL</i> 4	NM	<i>AL</i> 2	<i>AL</i> 4
f_1	3.5	7	8	5	1.99999	1.92189	2.99158
f_2	1.7	4	5	3	2.19212	1.89891	3.55514
f_3	1.5	6	34	4	2.05039	1.97063	3.18850
f_4	2	5	6	4	2.17194	2.10516	3.42355
f_5	2	9	34	5	2.03511	1.03401	3.17161
f_6	2	5	6	3	2.06888	1.97365	3.42128
f_7	7	4	5	3	2.38378	2.16311	4.17738
f_8	0.5	6	14	5	1.94071	1.86901	2.00000

The computational results presented in Table 1 shows that the suggested methods are comparable with Newton Method. This means that; the new methods (Algorithm 4 in particular) can be considered as a significant improvement of Newton Method, hence; they can serve as an alternative to other second and third order convergent respectively, methods of solving nonlinear equations.

VI. CONCLUSION

We derived a two step family of iterative methods based on composite trapezoidal rule and fundamental theorem of calculus, for solving nonlinear equations. Convergence proof is presented in detail for algorithm 2 and 4 and they are of order two and three respectively. Analysis of efficiency showed that these methods can be used as alternative to other existing order two and three iterative methods for zero of nonlinear equations. Finally, we hoped that this study makes a contribution to solve nonlinear equations.

REFERENCES

- [1] T. Yamamoto, *Historical development in convergence analysis for Newton's and Newton-like methods*, J. Comput. Appl. Math., **124**(2000), 1–23.
- [2] J. E. Dennis and R. B. Schnable, *Numerical Methods for Unconstrained Optimization and Nonlinear Equations* (Prentice Hall, 1983).
- [3] R. Ezzati and E. Azadegan, A simple iterative method with fifth-order convergence by using Potra and Ptak's method, Mathematical Sciences, Vol. 3(2009), No. 2, 191-200.
- [4] G. Fernandez-Torres, F. R. Castillo-Soria, and I. Algredo-Badillo, *Fifth and Sixth-Order Iterative Algorithms without Derivatives for Solving Non-Linear Equations*, International Journal of Pure and Applied Mathematics, **83**(1)(20013) 111-119.
- [5] Z. Fiza and A. M. Nazir, *A generalized family of quadrature based iterative methods*, General Mathematics Vol. 18 (2010), No. 4, 43-51.
- [6] T. Hadi, *New Iterative Methods Based on Spline Functions for Solving Nonlinear Equations*, Bullettin of Mathematical Analysis and Applications, Vol. 3(2011) Issue 4, 31-37.
- [7] M. M. Hosseini, A Note on One-step iteration Methods for Solving Nonlinear Equations, World Applied Science Journal 7(2009): 90-95.
- [8] S. Kumar, V. Kanwar and S. Singh S, *Modified Efficient Families of Two and Three-Step Predictor-Corrector Iterative Methods for Solving Nonlinear Equations*, Applied Mathematics, 1(2010), 153-158.
- [9] M, Matinfar and M. Aminzadeh, A family of optimal iterative methods with fifth and tenth order convergence for solving nonlinear equations, Journal of Interpolation and Approximation in Scientific Computing, Vol. 2012, 1-11.
- [10] M. A. Noor, K. I. Noor and K. Aftab, *Some New Iterative Methods for Solving Nonlinear Equations*, World Applied Science Journal, **20**(6)(2012):870-874.
- [11] K. R. Saeed and M. K. Aziz, *Iterative methods for solving nonlinear equations by using quadratic spline functions*, Mathematical Sciences Letters, **2**(2013), No.1, 37-43.
- [12] F. Soleymani, A Note on a Family of Zero-Finder Fourth-Order Methods for Nonlinear Equations, Journal of Mathematical Research, **2**(3) (2010), 43-46.
- [13] H. Zhongyong, G. Liu and T. Li, *An Iterative Method with Nith-Order Convergence for Solving Nonlinear Equations*, Int. J. Contemp. Math. Sciences. Vol. 6(2011), No. 1, 17-23.
- [14] M. Grau-Sanchez, M, Noguera, A. Grau, and R. J. Herreoro R. J., *A study on new computational local orders of convergence*, ar.Xiv:1202.4236v1[math.Na], 2012.